

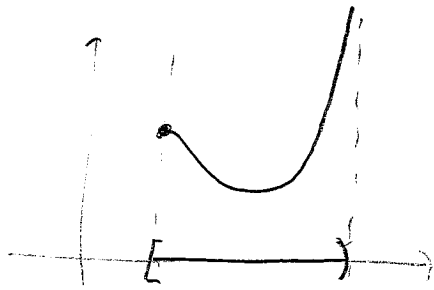
Remark: we will prove the theorem for  $n \geq 3$ , leaving the case  $n=2$  as exercise.

In order to prove the theorem, we will need the following facts.

Fact 1: Let  $K$  be a closed and bounded set in  $\mathbb{R}^n$ . Bounded means that  $K$  is contained in a ball of radius  $R$  and center zero for some  $R$ , i.e.

$K \subseteq B_R(0)$ . Let  $f: K \rightarrow \mathbb{R}$  be continuous. Then  $f$  attains a maximum and a minimum within  $K$ , thus there exists constants a constant  $M$  such that

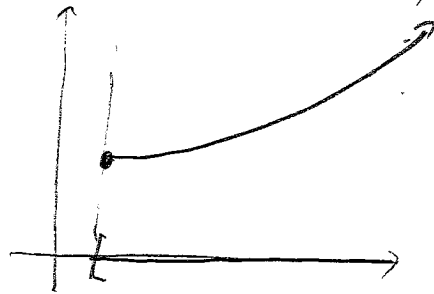
$|f(x)| \leq M$  for all  $x \in K$ . The following pictures illustrate this fact:



$K$  bounded but not closed

$f$  continuous

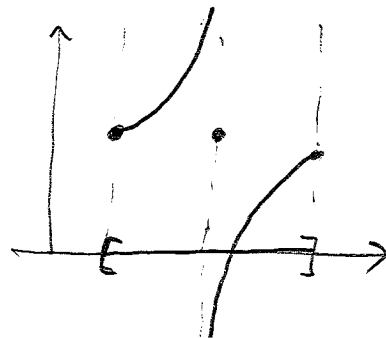
Fact 1 not true



$K$  closed but not bounded

$f$  continuous

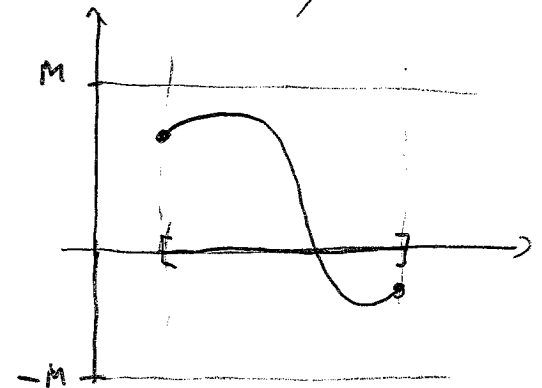
Fact 1 not true



$K$  closed and bounded

$f$  not continuous

Fact 1 not true



$K$  closed and bounded

$f$  continuous

Similar pictures can be drawn in higher dimensions

Fact 2 Let  $B_R(0)$  be the ball of radius  $R$  centered at the origin in  $\mathbb{R}^n$ . The volume element  $dx$  ( $= dv$  in 3d calculus) in  $B_r(0)$  can be written as  $dx = r^{n-1} dr d\Omega$ , where  $d\Omega$  is the volume element on  $\partial B_1(0)$ .

2d:  $dx = r dr d\theta$  ; 3d:  $dx = r^2 \sin\phi dr d\phi d\theta = r^2 dr \underbrace{\sin\phi d\phi d\theta}_{d\Omega}$

It follows that the volume element  $dS$  on  $\partial B_r(0)$  is  $dS = r^{n-1} d\Omega$

2d:  $dS = r d\theta$  ; 3d:  $dS = r^2 \sin\phi d\phi d\theta$

Fact 3 Let  $f$  be a  $C^2$  function. Then

$$\frac{1}{\text{vol}(\partial B_r(x_0))} \int_{\partial B_r(x_0)} f dS \longrightarrow f(x_0) \text{ as } r \rightarrow 0$$

M-i.e that

$$\text{vol}(\partial B_r(x_0)) = n \alpha(n) r^{n-1}$$

average of  $f$  over  $\partial B_r(x_0)$

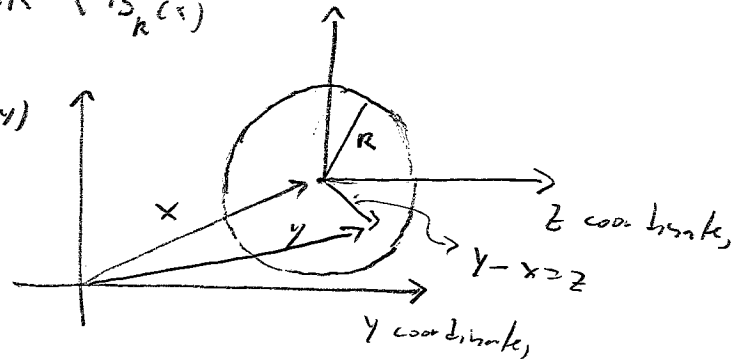
proof of the theorem

To show that  $u$  is well-defined, fix  $x \in \mathbb{R}^n$  and  $R > 0$  (say,  $R=1$ ), and write

$$u(x) = \int_{\mathbb{R}^n} \Gamma(x-y) f(y) dy = \int_{B_R(x)} \Gamma(x-y) f(y) dy + \int_{\mathbb{R}^n \setminus B_R(x)} \Gamma(x-y) f(y) dy$$

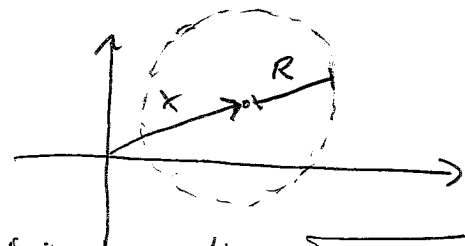
Change variables in the first integral:  $z = y-x = -(x-y)$

$$\int_{B_R(x)} \Gamma(x-y) f(y) dy = \int_{B_R(0)} \Gamma(-z) f(z+x) dz$$



As  $z$  varies within  $B_R(0)$ ,  $z+x$  varies within  $B_{R+|x|}(0)$ .

Since  $B_{R+|x|}(0) \subset \overline{B_{2(R+|x|)}(0)}$  and  $f$  attains a maximum and a minimum within  $\overline{B_{2(R+|x|)}(0)}$  we have that  $|f(z+x)| \leq M$  for some  $M$  and all  $z \in B_R(0)$ .



$$\text{Next, } \Gamma(-z) = \frac{1}{\Gamma(n-2) \pi^{n/2}} \frac{1}{|z|^{n-2}} = \frac{1}{\Gamma(n-2) \pi^{n/2}} \frac{1}{|z|^{n-2}}$$

Hence:

$$|\Gamma(-z)| = \Gamma(-z) \text{ since } \Gamma \geq 0$$

$$\left| \int_{B_R(0)} \Gamma(-z) f(z+x) dz \right| \leq \int_{B_R(0)} \Gamma(z) |f(z+x)| dz \leq M \int_{B_R(0)} \Gamma(z) dz = \frac{M}{n(n-2)\alpha(n)} \int_{B_R(0)} \frac{1}{|z|^{n-2}} dz$$

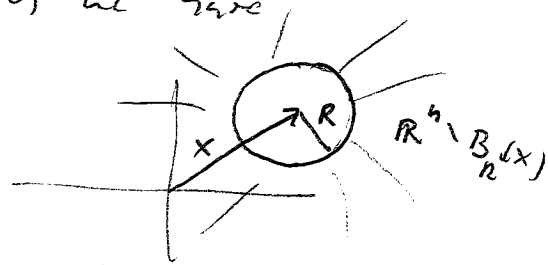
Integrating in polar coordinates:

$$\int_{B_R(0)} \frac{1}{|z|^{n-2}} dz = \int_0^R \int_{\partial B_r(0)} \frac{1}{r^{n-2}} dS = \int_0^R \frac{1}{r^{n-2}} \int_{\partial B_1(0)} r^{n-1} d\Omega$$

$$= \omega_{n-1} \int_0^R r dr = \frac{\omega_{n-1}}{2} R^2. \text{ Thus } \left| \int_{B_R(x)} \Gamma(x-y) f(y) dy \right| < \infty.$$

For the second integral, note that for any  $y \in \mathbb{R}^n \setminus B_R(0)$  we have

$$\Gamma(x-y) = \frac{1}{n(n-2)\alpha(n)} \frac{1}{|x-y|^{n-2}} \leq \frac{1}{n(n-2)R^{n-2}} \text{ since } |x-y| \geq R$$



Since  $f$  has compact support, and is continuous, we have  $|f(y)| \leq M$  for all  $y \in \mathbb{R}^n$ , thus

$$\left| \int_{\mathbb{R}^n \setminus B_R(x)} \Gamma(x-y) f(y) dy \right| \leq \int_{\mathbb{R}^n \setminus B_R(x)} \Gamma(x-y) |f(y)| dy < \infty, \text{ hence } |u(x)| < \infty, \text{ showing (i).}$$

Remark: we could have used  $|f(y)| \leq M, y \in \mathbb{R}^n$ , as the estimate of the first

integral, thus avoiding the argument with  $B_{|x|+R}^{(0)}$  etc. But we think it is useful to show that the first integral is  $< \infty$  without using that  $f$  has compact support, as that trick is generally useful.

To show (ii), change variables:

$$u(x) = \int_{\mathbb{R}^n} \underbrace{\Gamma(x-y)}_z f(y) dy = \int_{\mathbb{R}^n} \Gamma(z) f(x-z) \underbrace{|\det \frac{\partial z_i}{\partial y_j}|}_{=1} dz = \int_{\mathbb{R}^n} \Gamma(y) f(x-y) dy$$

For  $h \neq 0$  and  $e_i = (0, 0, \dots, \underset{\substack{\downarrow \\ i\text{th component}}}{1}, \dots, 0, 0)$ , we have

$$\frac{u(x+he_i) - u(x)}{h} = \int_{\mathbb{R}^n} \Gamma(y) \frac{f(x+he_i-y) - f(x-y)}{h} dy = \int_{\mathbb{R}^n} \Gamma(y) \left( \frac{f(x+he_i-y) - f(x-y)}{h} \right) dy$$

But  $\frac{f(x+he_i-y) - f(x-y)}{h} \rightarrow \frac{\partial f}{\partial x_i}(x-y)$  uniformly on  $\mathbb{R}^n$  as  $h \rightarrow 0$ . Since  $\frac{\partial f}{\partial x_i}$  is continuous, the same argument as in (i) shows that  $\int_{\mathbb{R}^n} \Gamma(y) \frac{\partial f}{\partial x_i}(x-y) dy < \infty$ , thus

$$\frac{\partial u}{\partial x_i}(x) = \lim_{h \rightarrow 0} \frac{u(x+he_i) - u(x)}{h} \text{ exists and } \frac{\partial u}{\partial x_i}(x) = \int_{\mathbb{R}^n} \Gamma(y) \frac{\partial f}{\partial x_i}(x-y) dy.$$

Using that  $\frac{\partial f}{\partial x_i}$  is continuous (because  $f$  is  $C^2$ ), we can then show that  $\frac{\partial u}{\partial x_i}$  is continuous, thus  $u \in C^1(\mathbb{R}^n)$ .

To show that  $\frac{\partial^2 u}{\partial x_i \partial x_j}$  exists, we repeat the above arguments applied to  $\frac{\partial u}{\partial x_i}$ .

To show that  $\frac{\partial^2 u}{\partial x_i \partial x_j}$ , we then use the continuity of  $\frac{\partial^2 f}{\partial x_i \partial x_j}$ . This establishes (i).

Exercise: complete the proof of (ii) by developing the above arguments.