

VANDERBILT UNIVERSITY  
MATH 196 — EXAMPLES OF SECTION 3.6

**Question 1.** Find the determinant of

$$A = \begin{bmatrix} 3 & 5 & 6 \\ 2 & 4 & 3 \\ 2 & 3 & 5 \end{bmatrix}$$

**Question 2.** Solve the system

$$A\vec{x} = \vec{b},$$

where  $A$  is the matrix of question 1 and

$$\vec{b} = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix},$$

by using the inverse of  $A$ .

**Question 3.** Solve the system of question 2 using Cramer's rule.

**SOLUTIONS.**

1. We have

$$A_{11} = \begin{bmatrix} 4 & 3 \\ 3 & 5 \end{bmatrix} \Rightarrow \det(A_{11}) = 4 \cdot 5 - 3 \cdot 3 = 11,$$

$$A_{12} = \begin{bmatrix} 2 & 3 \\ 2 & 5 \end{bmatrix} \Rightarrow \det(A_{12}) = 2 \cdot 5 - 3 \cdot 2 = 4,$$

$$A_{13} = \begin{bmatrix} 2 & 4 \\ 2 & 3 \end{bmatrix} \Rightarrow \det(A_{13}) = 2 \cdot 3 - 2 \cdot 4 = -2.$$

Hence,

$$\det(A) = 3 \det(A_{11}) - 5 \det(A_{12}) + 6 \det(A_{13}) = 33 - 20 - 12 = 1.$$

2. Write

$$\begin{bmatrix} 3 & 5 & 6 & \vdots & 1 & 0 & 0 \\ 2 & 4 & 3 & \vdots & 0 & 1 & 0 \\ 2 & 3 & 5 & \vdots & 0 & 0 & 1 \end{bmatrix}$$

and apply Gauss-Jordan elimination.

$$\begin{bmatrix} 3 & 5 & 6 & \vdots & 1 & 0 & 0 \\ 2 & 4 & 3 & \vdots & 0 & 1 & 0 \\ 2 & 3 & 5 & \vdots & 0 & 0 & 1 \end{bmatrix} \xrightarrow{L_1 \leftarrow L_1 - L_2} \begin{bmatrix} 1 & 1 & 3 & \vdots & 1 & -1 & 0 \\ 2 & 4 & 3 & \vdots & 0 & 1 & 0 \\ 2 & 3 & 5 & \vdots & 0 & 0 & 1 \end{bmatrix} \xrightarrow{L_2 \leftarrow L_2 - L_3}$$

$$\begin{bmatrix} 1 & 1 & 3 & \vdots & 1 & -1 & 0 \\ 0 & 1 & -2 & \vdots & 0 & 1 & -1 \\ 2 & 3 & 5 & \vdots & 0 & 0 & 1 \end{bmatrix} \quad L_3 \leftarrow \underbrace{L_3 - 2L_1} \quad \begin{bmatrix} 1 & 1 & 3 & \vdots & 1 & -1 & 0 \\ 0 & 1 & -2 & \vdots & 0 & 1 & -1 \\ 0 & 1 & -1 & \vdots & -2 & 2 & 1 \end{bmatrix}$$

$$L_3 \leftarrow \underbrace{L_3 - L_2} \quad \begin{bmatrix} 1 & 1 & 3 & \vdots & 1 & -1 & 0 \\ 0 & 1 & -2 & \vdots & 0 & 1 & -1 \\ 0 & 0 & 1 & \vdots & -2 & 1 & 2 \end{bmatrix} \quad \begin{array}{l} L_2 \leftarrow 2L_3 + L_2 \\ L_2 \leftarrow \underbrace{-3L_3 + L_1} \end{array}$$

$$\begin{bmatrix} 1 & 1 & 0 & \vdots & 7 & -4 & -6 \\ 0 & 1 & 0 & \vdots & -4 & 3 & 3 \\ 0 & 0 & 1 & \vdots & -2 & 1 & 2 \end{bmatrix} \quad L_1 \leftarrow \underbrace{L_1 - L_2} \quad \begin{bmatrix} 1 & 0 & 0 & \vdots & 11 & -7 & -9 \\ 0 & 1 & 0 & \vdots & -4 & 3 & 3 \\ 0 & 0 & 1 & \vdots & -2 & 1 & 2 \end{bmatrix}$$

So

$$A^{-1} = \begin{bmatrix} 11 & -7 & -9 \\ -4 & 3 & 3 \\ -2 & 1 & 2 \end{bmatrix}.$$

Therefore

$$\vec{x} = A^{-1}\vec{b} = \begin{bmatrix} 11 & -7 & -9 \\ -4 & 3 & 3 \\ -2 & 1 & 2 \end{bmatrix} \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix} = \begin{bmatrix} -14 \\ 6 \\ 2 \end{bmatrix}.$$

3. Replace the first column of A with  $\vec{b}$  to get:

$$A_1(\vec{b}) = \begin{bmatrix} 0 & 5 & 6 \\ 2 & 4 & 3 \\ 0 & 3 & 5 \end{bmatrix}.$$

Analogously, replacing the second and third column produces

$$A_2(\vec{b}) = \begin{bmatrix} 3 & 0 & 6 \\ 2 & 2 & 3 \\ 2 & 0 & 5 \end{bmatrix},$$

and

$$A_3(\vec{b}) = \begin{bmatrix} 3 & 5 & 0 \\ 2 & 4 & 2 \\ 2 & 3 & 0 \end{bmatrix}$$

Then

$$\det(A_1(\vec{b})) = 0 \cdot \det \begin{bmatrix} 4 & 2 \\ 3 & 0 \end{bmatrix} - 2 \cdot \det \begin{bmatrix} 5 & 6 \\ 3 & 5 \end{bmatrix} + 0 \cdot \det \begin{bmatrix} 5 & 6 \\ 4 & 3 \end{bmatrix} = -14.$$

Analogously,

$$\det(A_2(\vec{b})) = -0 \cdot \det \begin{bmatrix} 2 & 3 \\ 2 & 5 \end{bmatrix} + 2 \cdot \det \begin{bmatrix} 3 & 6 \\ 2 & 5 \end{bmatrix} - 0 \cdot \det \begin{bmatrix} 3 & 6 \\ 2 & 3 \end{bmatrix} = 6,$$

$$\det(A_3(\vec{b})) = 0 \cdot \det \begin{bmatrix} 2 & 4 \\ 2 & 3 \end{bmatrix} - 2 \cdot \det \begin{bmatrix} 3 & 5 \\ 2 & 3 \end{bmatrix} + 0 \cdot \det \begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix} = 2.$$

We finally obtain

$$x_1 = \frac{\det(A_1(\vec{b}))}{\det(A)} = \frac{-14}{1} = -14,$$

$$x_2 = \frac{\det(A_2(\vec{b}))}{\det(A)} = \frac{6}{1} = 6,$$

$$x_3 = \frac{\det(A_3(\vec{b}))}{\det(A)} = \frac{2}{1} = 2,$$

in accordance to what we found in question 2.

*URL:* <http://www.disconzi.net/Teaching/MAT196-Spring-15/MAT196-Spring-15.html>